

## CDT Hilary Term Lecture Timetable 2019

All lectures will take place in LR7, Information Engineering Building, unless stated otherwise.

	Monday	Tuesday	Wednesday	Thursday	Friday
<b>Week 0</b> Week beg 07/1/19		<b>Intro to Linux/Unix</b>  Susan Hutchinson  <i>Software Lab B</i> 10:00 – 12:00		<b>Core Writing Skills</b>  John Dixon  <i>LR7</i> 09:00 – 17:00	<b>IP@Oxford &amp; Beyond</b>  Oxford University Innovation  <i>LR7</i> 09:30-12:30
<b>Week 1</b> Week beg 14/1/19	<b>Computer Vision</b>  10:00 – 12:00	<b>Computer Vision</b>  10:00 – 12:00	<b>Computer Vision</b>  10:00 – 12:00	<b>Computer Vision</b>  10:00 – 12:00	<b>Computer Vision</b>  10:00 – 12:00
<b>Week 2</b> Week beg 21/1/19	<b>Systems Verification</b>  10:00 – 13:00	<b>Systems Verification</b>  10:00 – 13:00	<b>Systems Verification</b>  10:00 – 13:00	<b>Systems Verification</b>  09:00 – 12:00	<b>Systems Verification</b>  10:00 – 13:00
<b>Week 3</b> Week beg 28/1/19	<b>Sensor Networks</b>  10:00 – 12:00	<b>Sensor Networks</b>  10:00 – 12:00	<b>Sensor Networks</b>  10:00 – 12:00	<b>Sensor Networks</b>  10:00 – 12:00	<b>Sensor Networks</b>  10:00 – 12:00
<b>Week 4</b> Week beg 04/2/19	<b>Computational Game Theory</b>  10:00 – 12:00	<b>Computational Game Theory</b>  10:00 – 12:00	<b>Computational Game Theory</b>  10:00 – 12:00	<b>Computational Game Theory</b>  10:00 – 12:00	<b>Computational Game Theory</b>  10:00 – 12:00
<b>Week 5</b> Week beg 11/2/19	<b>Dynamic Robot Locomotion and Motion</b>  09:00 – 17:00	<b>Dynamic Robot Locomotion and Motion</b>  09:00 – 17:00	<b>Dynamic Robot Locomotion and Motion</b>  09:00 – 17:00	<b>Dynamic Robot Locomotion and Motion</b>  09:00 – 17:00	<b>Dynamic Robot Locomotion and Motion</b>  09:00 – 17:00
<b>Week 6</b> Week beg 18/2/19	<b>Reinforcement Learning</b>  10:00 – 12:30	<b>Reinforcement Learning</b>  10:00 – 12:30	<b>Reinforcement Learning</b>  10:00 – 12:30	<b>Reinforcement Learning</b>  10:00 – 12:30	
<b>Week 7</b> Week beg 25/2/19	<b>Privacy &amp; Security in Wireless Networks</b>  10:00 – 12:30 14:00 – 17:00 (LR1)	<b>Privacy &amp; Security in Wireless Networks</b>  10:00 – 12:30 14:00 – 17:00 (LR1)	<b>Privacy &amp; Security in Wireless Networks</b>  10:00 – 12:30	<b>Privacy &amp; Security in Wireless Networks</b>  10:00 – 12:30	<b>Privacy &amp; Security in Wireless Networks</b>  10:00 – 12:30

<b>Week 8</b> <b>Week beg</b> <b>04/3/19</b>	<b>Mobile Robotics (ORI)</b>  <i>09:00 – 17:00</i>	<b>Mobile Robotics (ORI)</b>  <i>09:00 – 17:00</i>	<b>Mobile Robotics (ORI)</b>  <i>09:00 – 17:00</i>	<b>Mobile Robotics (ORI)</b>  <i>09:00 – 17:00</i>	<b>Mobile Robotics (ORI)</b>  <i>09:00 – 17:00</i>
<b>Week 9</b> <b>11/3/19</b>	<b>Project Presentations</b>  <b>LR7</b>  <b>14:00 – 16:00</b>	<b>Project Presentations</b>  <b>LR7</b>  <b>14:00 – 16:00</b>			

### **Computer Vision**

Lecturer(s) – Andrew Zisserman, Andrea Vedaldi and Victor Prisacariu

Lab Demonstrators –

### **Systems Verification**

Lecturer(s) – Daniel Kroening, Marta Kwiatkowska and Alessandro Abate

Lab Demonstrators – Maciej Olejnik

### **Privacy and Security in Wireless Networks**

Lecturer(s) – Ivan Martinovic

Lab Demonstrators –

### **Computational Game Theory**

Lecturer(s) – Mike Wooldridge

Lab Demonstrators – Muhammad Najib and Jiarui Gan

### **Walking Robots**

Lecturer(s) – Maurice Fallon and Ioannis Havoutis

Lab Demonstrators -

### **Reinforcement Learning**

Lecturer(s) – Shimon Whiteson

Lab Demonstrators - Jelena Luketina , Luisa Zintgraf, Wendelin Boehmer, Anuj Mahajan, Matt Fellows, Supratik Paul, Max Igl and Greg Farquhar

### **Sensor and Actuator Networks**

Lecturer(s) – Andrew Markham

Lab Demonstrators – Xiaoxuan Lu

### **Mobile Robotics**

Lecturer(s) – Paul Newman and Ingmar Posner

Lab Demonstrators -

## CDT Hilary Term Lab Timetable 2019

All lab sessions will take place in the student area, 8<sup>th</sup> Floor, Thom Building, unless stated otherwise.

	Monday	Tuesday	Wednesday	Thursday	Friday
<b>Week 1</b> Week beg 15/1/18	<b>Computer Vision</b>  <i>14:00 – 17:00</i>	<b>Computer Vision</b>  <i>14:00 – 17:00</i>			<b>Computer Vision</b>  <i>14:00 – 17:00</i>
<b>Week 2</b> Week beg 22/1/18	<b>Systems Verification</b>  <i>14:30 – 17:00</i>	<b>Systems Verification</b>  <i>14:30 – 17:00</i>	<b>Systems Verification</b>  <i>14:30 – 17:00</i>		<b>Systems Verification</b>  <i>14:30 – 17:00</i>
<b>Week 3</b> Week beg 29/1/18		<b>Sensor and Actuator Networks</b>  <i>14:00 - 16:30</i>		<b>Sensor and Actuator Networks</b>  <i>14:00 - 16:30</i>	<b>Sensor and Actuator Networks</b>  <i>14:00 - 16:30</i>
<b>Week 4</b> Week beg 5/2/18		<b>Computational Game Theory</b>  <i>14:00 – 17:00</i>	<b>Presentation Skills</b> <i>JSR Seminar room, Physical and Theoretical Chemistry</i>  <i>2.00-5.00</i>	<b>Computational Game Theory</b>  <i>14:00 – 17:00</i>	<b>Computational Game Theory</b>  <i>14:00 – 17:00</i>
<b>Week 5</b> Week beg 12/2/18	<b>Dynamic Robot Locomotion and Motion</b>  <i>09:00 – 17:00</i>	<b>Dynamic Robot Locomotion and Motion</b>  <i>09:00 – 17:00</i>	<b>Dynamic Robot Locomotion and Motion</b>  <i>09:00 – 17:00</i>	<b>Dynamic Robot Locomotion and Motion</b>  <i>09:00 – 17:00</i>	<b>Dynamic Robot Locomotion and Motion</b>  <i>09:00 – 17:00</i>
<b>Week 6</b> Week beg 19/2/18	<b>Reinforcement Learning</b>  <i>14:00 – 17:00</i>	<b>Reinforcement Learning</b>  <i>14:00 – 17:00</i>	<b>Reinforcement Learning</b>  <i>14:00 – 17:00</i>	<b>Reinforcement Learning</b>  <i>14:00 – 17:00</i>	
<b>Week 7</b> Week beg 26/2/18			<b>Privacy &amp; Security in Wireless Networks</b>  <i>14:00 – 17:00</i>	<b>Privacy &amp; Security in Wireless Networks</b>  <i>14:00 – 17:00</i>	<b>Privacy &amp; Security in Wireless Networks</b>  <i>14:00 – 17:00</i>
<b>Week 8</b> Week beg 5/3/18	<b>Mobile Robotics (ORI)</b>  <i>09:00 – 17:00</i>	<b>Mobile Robotics (ORI)</b>  <i>09:00 – 17:00</i>	<b>Mobile Robotics (ORI)</b>  <i>09:00 – 17:00</i>	<b>Mobile Robotics (ORI)</b>  <i>09:00 – 17:00</i>	<b>Mobile Robotics (ORI)</b>  <i>09:00 – 17:00</i>

